

uRAD Industrial v2.0

60 GHz radar, velocity and 3D positioning

DESCRIPTION

uRAD Industrial v2.0 is a **millimeter wave radar sensor** which presents outstanding measurement capabilities in a very compact size. Based on the **IWR6843AoP chip of Texas Instruments**, uRAD detects range, velocity and angle of objects with unprecedented accuracy and robustness.

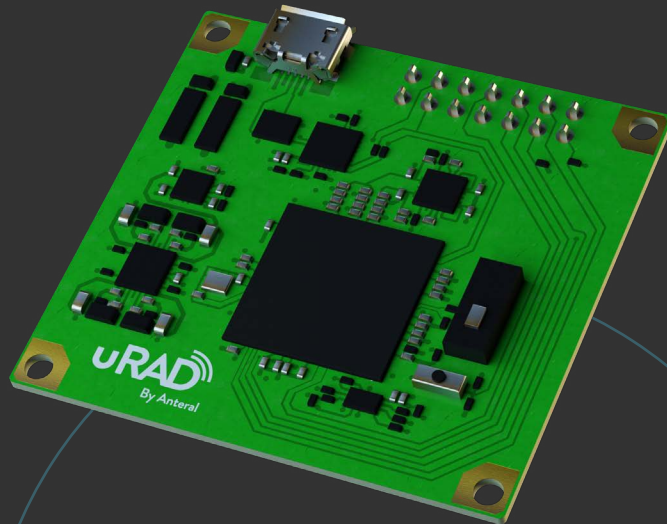
Working at the **60-64 GHz frequency band**, uRAD exhibits up to three times higher spatial and velocity resolution than others solutions in the market. Connect uRAD and discover the power of radar technology for industrial and smart cities applications!

APPLICATIONS

uRAD is conceived as an evaluation platform to develop new and innovative applications. Leverage the open and free software of Texas Instruments to develop your own projects. You will have access to many laboratories to test different applications from the beginning.

Thanks to uRAD, you will be able to develop and create **applications** as:

- POINTS CLOUD VISUALIZER
- AREA SCANNER
- AUTOMATED DOORS
- GESTURE RECOGNITION
- LEVEL SENSING
- PEOPLE COUNTING
- ROBOTICS
- TRAFFIC MONITORING
- VITAL SIGNS



OPERATING CONDITIONS

Parameter	Typical value	Notes
Supply voltage	4.5 - 5.5 V	By USB or 10-pin connector
Supply current	340 mA	Depend on the application
Operating temperature	-20 to +85 °C	

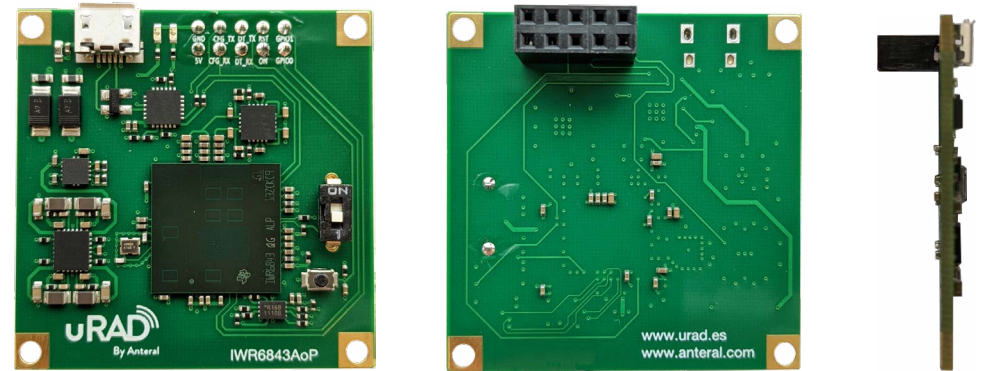
RF PARAMETERS

Parameter	Typical value	Notes
Frequency bandwidth	60 - 64 GHz	
Output power	15 dBm	EIRP (including antenna gain)
Number of transmitter antennas	3	Antenna on package
Number of receiver antennas	4	Antenna on package
Azimuthal field of view	160	deg
Elevation field of view	160	deg

DIMENSIONS

Parameter	Typical value
Dimensions	42 x 42 x 10 mm
Weight	5 gr

OUTLINE



PERFORMANCE

Parameter	
Mode of operation	Frequency Modulated Continuous Wave
Output data	Distance, velocity, angle and SNR (signal to noise ratio)
Distance range	70 m (car), 40m (people)
Distance accuracy	±1 mm
Distance resolution	5 cm
Velocity range	45 m/s
Velocity accuracy	±0.15 m/s
Velocity resolution	0.06 m/s
Angle accuracy	1 deg
Azimuthal angle resolution	30 deg
Elevation angle resolution	30 deg

Distance and velocity range, accuracy and resolution values depend on the configuration parameters of the transmitted waveform.

Resolution indicates the minimum distance, velocity or angle that two targets with similar reflectivity must be separated to be discerned as a single target each one.

OTHER

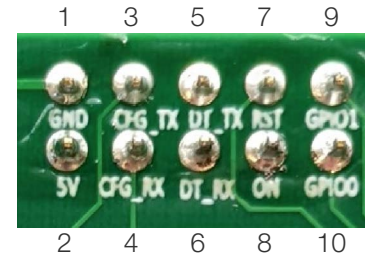
uRAD team, as experts in radar technology, also develops custom software and firmware to exploit the most out of capabilities of our radars.

Contact us at contact@urad.es if you want to know more about these additional services.

COMMUNICATION

The board has two different connections:

- Micro USB connector: power, upload firmware, send configuration, receive data.
- Female 10-Pin header connector: power, send configuration, receive data, reset, ON/OFF and GPIOs.



- | | |
|-------------------|-----------------|
| 1: GND | 6: UART RX data |
| 2: 5V | 7: Reset |
| 3: UART TX config | 8: ON/OFF |
| 4: UART RX config | 9: GPIO1 |
| 5: UART TX data | 10: GPIO0 |

SOFTWARE AND FIRMWARE

uRAD core is the IWR6843AoP chip of Texas Instruments. Therefore, you have access to all software and documentation available about it:

- Flash any firmware, including the mmWave SDK by the USB connector.
- Or create your own firmware with Code Composer Studio and upload it.
- Test any already programmed application laboratory in your computer by the USB or 10-pin connector.
- Use (configure and get data) with the USB or 10-pin connector.

Moreover, with the purchase it is also included:

- Standard firmware for point cloud detection.
- Open libraries in Python for configuring and getting results.
- Examples of use.
- Support by our radar experts regarding any doubt you have about radar configuration.

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